The EISCAT_3D Preparatory Phase Project

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On behalf of the EISCAT_3D Project Consortium

EISCAT: 5-10 years from now

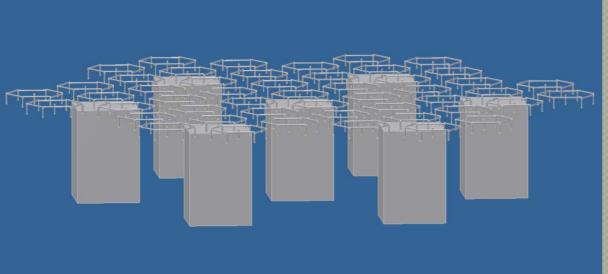
The EISCAT_3D Vision

The most sophisticated research radar ever!

Five key capabilities:
Volumetric imaging and tracking
Aperture Synthesis imaging
Multistatic configuration
Greatly improved sensitivity
Transmitter flexibility

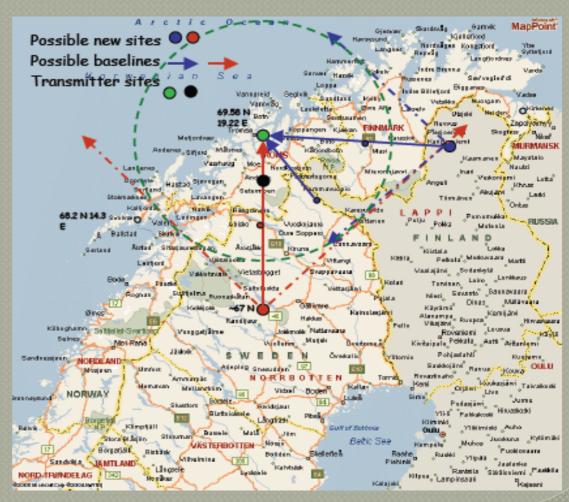
These abilities never before combined in a single radar

The EISCAT_3D Vision

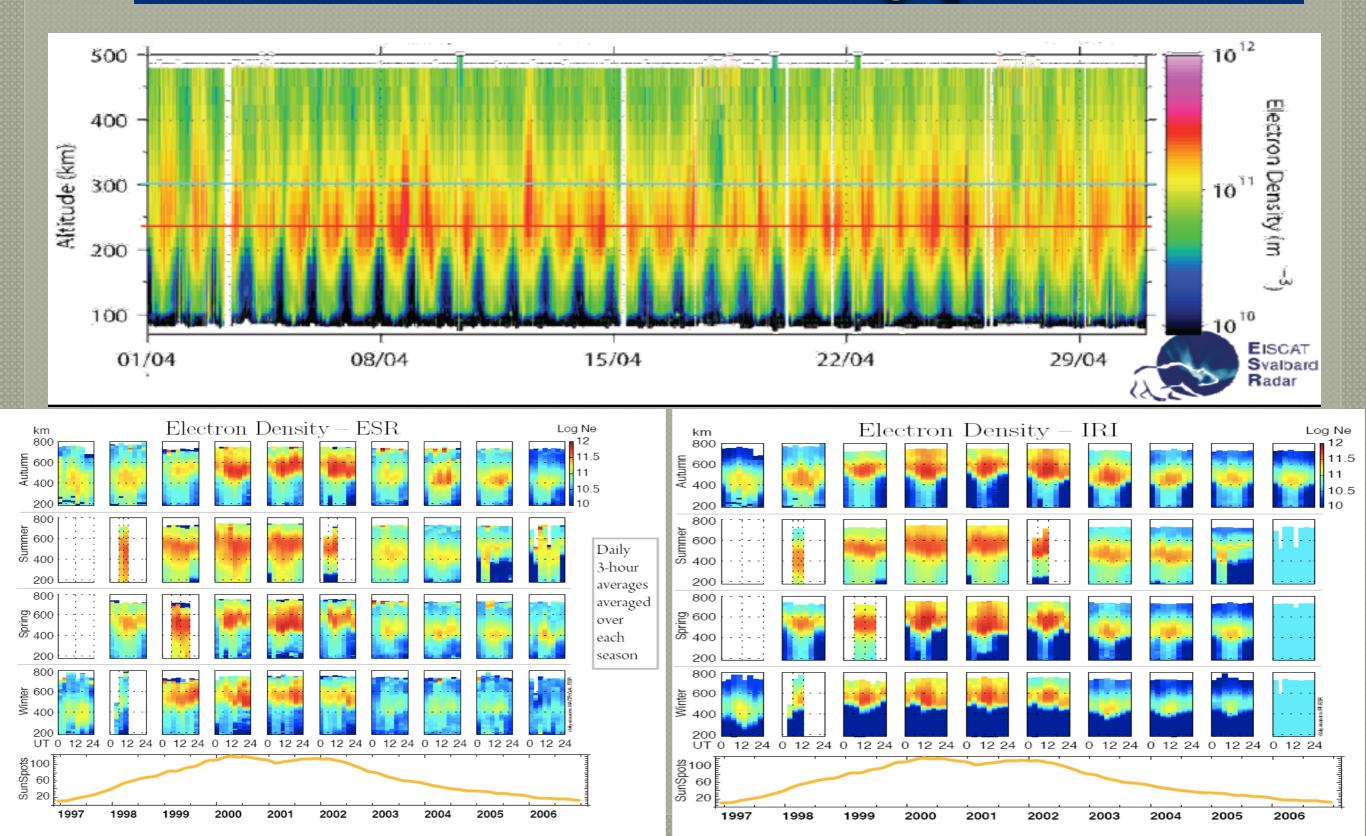


•Replace mainland system with multi-static system, comprising both transmit/receive and passive arrays

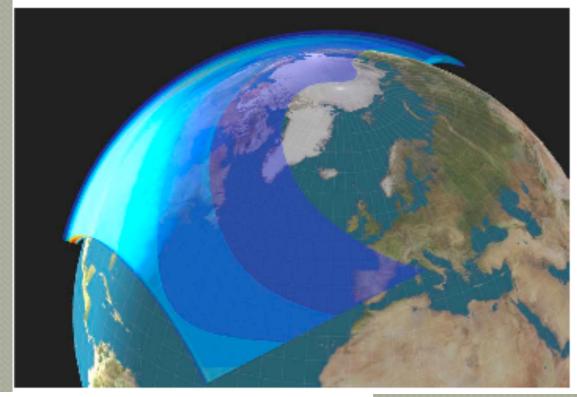
•Integrated multi-beam and imaging capabilities

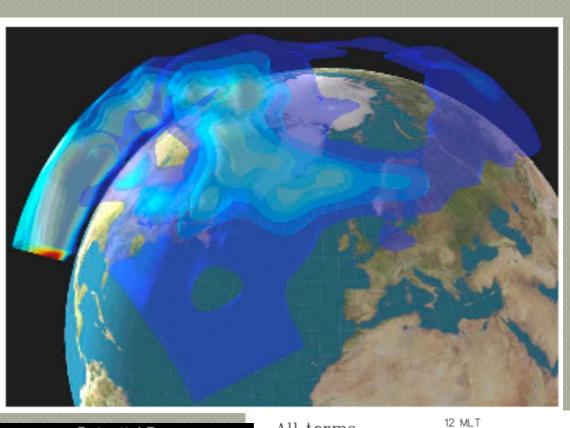


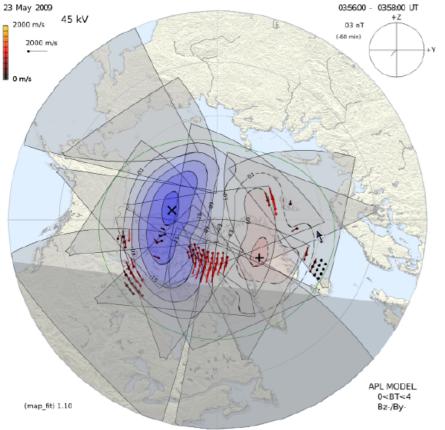
Continuous, long-period data

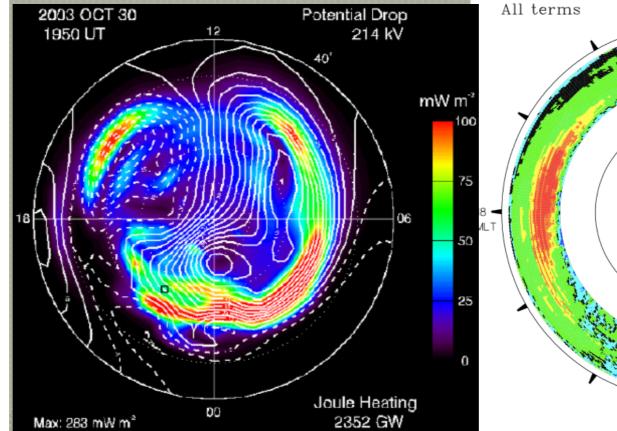


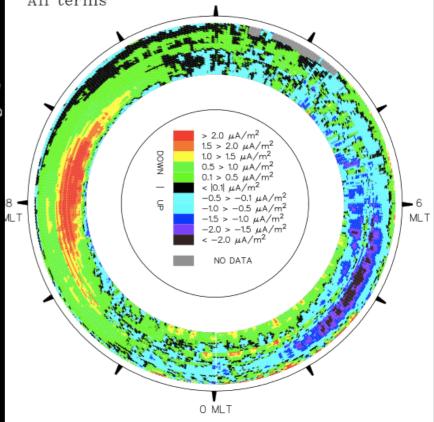
Large-scale monitoring





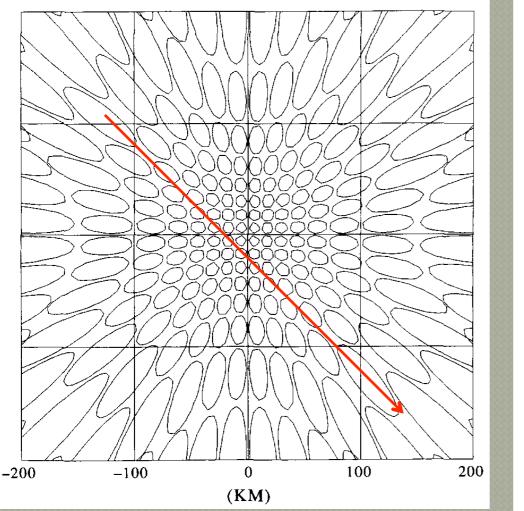




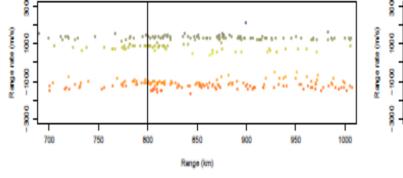


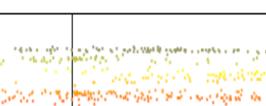
Space Situational Awareness

Î



UHF Observation (Range vs. Time) PROOF simulation (Range vs. Time) 8 8 8 8 20 15 Time (UT) Time (UT) UHF Observation (Vel vs. Range) PROOF cimulation (Vel vc. Range)





Range (km)

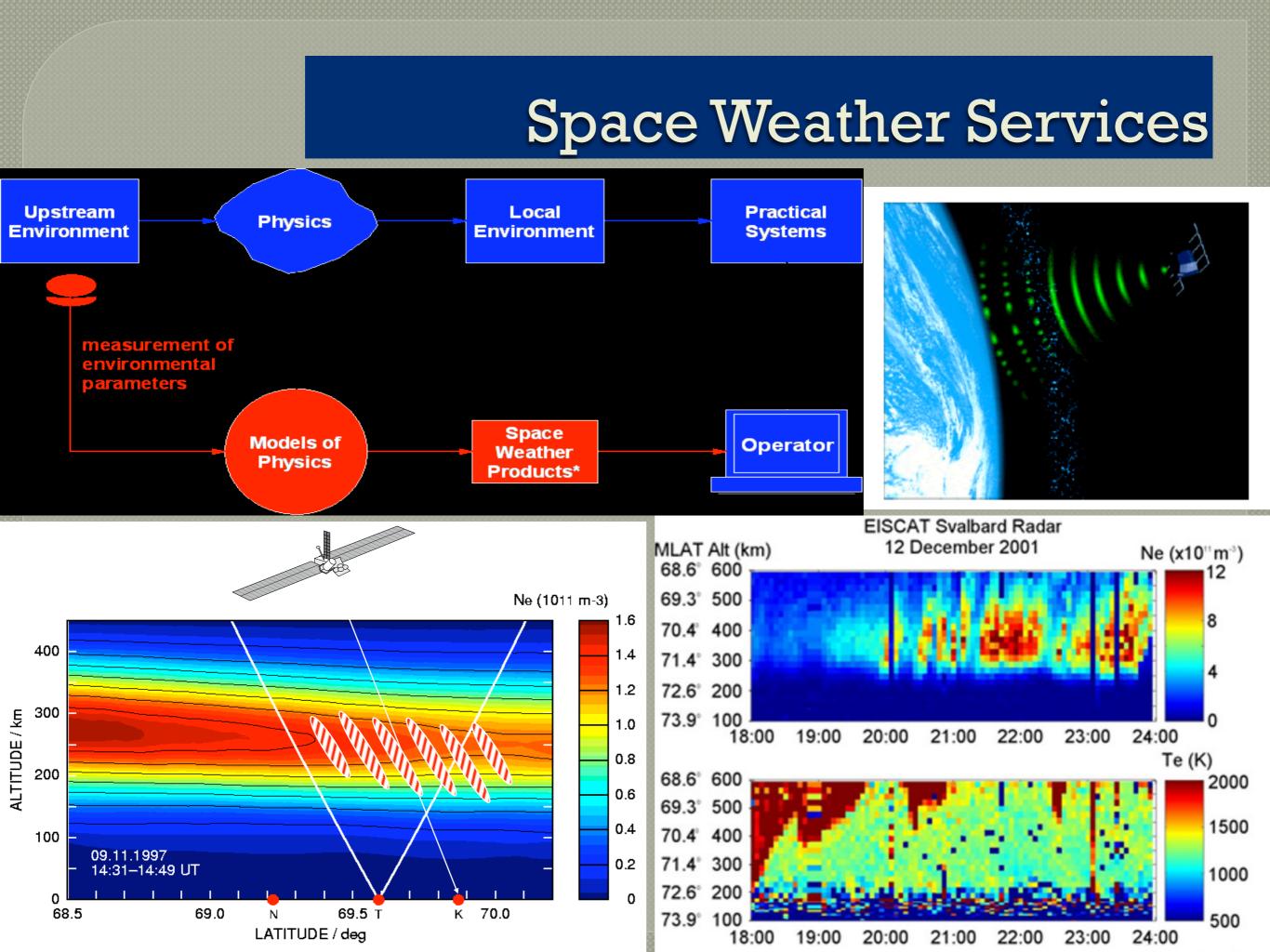
750

15

space situational awareness

European Space Agency

20



FP7 Preparatory Phase

Application : December 4 2009

14 work packages:

WP1: Management and reporting
WP2: Legal and logistical issues
WP3: Science planning
WP4: Outreach activities
WP5: Consortium building
WP6: Performance specification
WP7: Signal processing
WP8: Antenna, front end and timing
WP9: Transmitter development
WP10: Aperture synthesis imaging
WP11: Software theory & implementation
WP12: System control
WP13: Data handling & distribution
WP14: Mass-production & reliability

TOTAL: 4.5M Euros



EISCAT_3D

A European Three-Dimensional Imaging Radar for Atmospheric and Geospace Research

Application for Preparatory Phase Funding under the European 7th Framework

Strategic Work

We need:

new partners
publicity
development of science case
new communities to broaden science base
frequency permissions
discussions with governments, local communities...
sites and building permissions
provision of infrastructure
manufacturers to build the system

Financial Work

We need to:

- In fully quantify the commitment needed
- build a financing consortium
- make a cost model for construction and operations
- develop material to be used in applications
- understand what, and when, the opportunities will be in each potential funding body
- decide how best to use the money we have

Technical Work

We need to:

- Revise and update Performance Specification
- Test the signal processing system
- Develop system software (DSP, coding, analysis)
- Evaluate all antenna options, test prototypes
- Develop and test front end and timing system
- Prototype and test the transmitters
- Optimise the imaging system
- Specify the data system implementation
- Clarify mass production and quality control

Roles of the Project Partners

- <u>EISCAT</u>: Project management and reporting, site selection, consortium building, performance specification, system control, mass production issues, outreach activities
- <u>University of Oulu:</u> Signal processing, software development, theory, science planning
- <u>University of Lulea</u>: Antenna, front end and timing synchronisation, mass production
- IRF Kiruna: Transmitter development
- <u>University of Tromsø:</u> Radar imaging, site selection
- STFC RAL: Science planning, performance specification, project management
- National Instruments: Signal processing and timing, mass production issues
- <u>VR-SNIC</u>: Data handling and distribution
- VR: Consortium building

Project started October 1st

•Kick-off meeting (Stockholm) •First meetings of project committees Science Working Group formed Project Manager vacancy will be advertised soon



Finnish Support Action: LOFAR



Frequency range	30 - 80 MHz 120 - 240 MHz
Polarisations	2
Bandwidth	32 MHz (currently 48 MHz investigated)
Spectral channels	
Stations	18 core
Baseline length	100 m to 1500 km
Simultaneous digital beams	8
Sample bit depth	12
Spectral resolution	0.76 kHz

LOFAR Panels at Kilpisjarvi:

Getting Involved

EISCAT_3D needs the Space Weather community!

Participate in our science working group

Become an "associate partner" of EISCAT_3D

Energise your national community

Annual Users Meetings at Uppsala, Sweden:

Next: May 18-20, 2011





Interact with the project

03-08.04.2011, EGU General Assembly, Vienna, Austria

 Session ST3.4 "Advance in ionospheric research by incoherent scatter radars, related radio methods and novel large observational systems"

18-20.05.2011, 3rd EISCAT_3D Users meeting, Uppsala, Sweden

- 1st day: Middle atmospheric science applications of EISCAT_D
- 2nd and 3rd day: User applications of EISCAT_3D, status and actions in the Preparatory Phase Project

13-20.08.2011 XXX URSI General Assembly and Scientific Symposium, Istanbul Turkey

 Sessions G05 and G06: "Coordinated Studies with Multiple Incoherent Scatter Radars" and "Recent Developments in Incoherent Scatter Radar", respectively

5-9.09.2011, 15th EISCAT International Workshop, Qingdao, China

• Session "The EISCAT_3D and the future"

14-22-07.2012 39th COSPAR Scientific Assembly, Mysore, India

 Session C04: New Generation Middle and Upper Atmosphere Radars: Application and Development

Opportunity for young people

18-22 July, 2011: Joint NSF - EISCAT incoherent scatter radar school, Kangerlussuaq, Greenland

